

**Amendments to the Claims:**

Please amend the claims as follows. This listing of claims will replace all prior versions, and listings, of claims in the application:

**Listing of Claims:**

1. (Currently Amended) A tool comprising:  
a tear-off edge;  
a grasper adapted to selectively grasp a tearable medium;  
a conveyor adapted to selectively move the grasper along a first axis to move the tearable medium against the tear-off edge to sever the tearable medium; and  
a controller adapted to transmit a first signal for instructing the conveyor to move the grasper and a second signal for instructing the grasper to grasp the tearable medium,  
wherein the tear-off edge extends along a second axis oblique to the first axis.
2. (Original) The tool of claim 1, wherein the grasper comprises first and second jaws adapted to grasp the tearable medium therebetween.
3. (Original) The tool of claim 2, wherein the first jaw comprises a pad for frictionally engaging the tearable medium.
4. (Original) The tool of claim 1, wherein the controller comprises a programmable logic device.
5. (Original) The tool of claim 2, wherein the grasper comprises an actuator adapted to move the first jaw into engagement with the tearable medium for grasping the tearable medium between the first and second jaws and to move the first jaw out of engagement with the tearable medium for releasing the tearable medium from between the first and second jaws.
6. (Original) The tool of claim 1, wherein the tear-off edge constitutes a part of a printer.

7. (Currently Amended) The tool of claim 2, wherein the first jaw is actuatable relative to the second jaw along a second third axis that forms an oblique angle with the first axis along which the conveyor moves the grasper.

8. (Original) The tool of claim 1, wherein the controller receives a signal that instructs the controller to transmit the first and second signals.

9. (Currently Amended) The tool of claim 1, and further comprising ~~an~~ electromagnetical a first electromechanical valve that receives the first signal from the controller, the first electromechanical valve passing a flow of fluid to the conveyor upon receiving the first signal for moving the grasper.

10. (Currently Amended) The tool of claim 2 9, wherein the grasper comprises first and second jaws adapted to grasp the tearable medium therebetween and further comprising ~~an~~ a second electromechanical valve that receives the second signal, the second electromechanical valve passing a flow of fluid to the grasper upon receiving the second signal for moving the first jaw into engagement with the tearable medium.

11. (Original) The tool of claim 1, wherein the conveyor comprises a carriage and at least one rail, the carriage slidably attached to the at least one rail and fixedly attached to the grasper.

12. (Currently Amended) A tool comprising:

a tear-off edge;

first and second jaws;

an actuator adapted to selectively move the first jaw along a first axis into engagement with a tearable medium to grasp the tearable medium between the first and second jaws and out of engagement with the tearable medium to release the tearable medium from between the first and second jaws;

a conveyor adapted to selectively move the first and second jaws along a second axis that forms an oblique angle with the first axis to move the tearable medium when grasped by the first and second jaws against the tear-off edge to sever the tearable medium; and

a controller adapted to transmit a first signal for instructing the conveyor to move the grasper from a first position, and a second signal for instructing the actuator to move the first jaw into engagement with the tearable medium.

13-20. Cancelled.

21. (Currently Amended) A tool for tearing printable media from an imaging device, the tool comprising:

a conveyor;

an actuator attached to the conveyor, the actuator including:

a slide;

a first jaw fixedly attached to the actuator;

a second jaw located opposite the first jaw and slidably attached to the slide of the actuator so as to linearly move towards and away from the first jaw;

a controller connected to the conveyor and the actuator; and

a tear-off edge, wherein the first jaw and the second jaw are configured to selectively grasp the printable medium and wherein the conveyor is configured to move the first jaw and the second jaw to move the printable medium against the tear-off edge, wherein the actuator is attached to the conveyor so that the slide of the actuator is oriented at an oblique angle with respect to the conveyor.

22. (Previously Amended) The tool of claim 21, wherein the second jaw comprises a pad.

23. (Original) The tool of claim 21, wherein the controller comprises a programmable logic device.

24. (Original) The tool of claim 21, and further comprising an electromechanical valve that is electrically connected to the controller and fluidly connected to the conveyor.

25. (Original) The tool of claim 21, and further comprising an electromechanical valve that is electrically connected to the controller and fluidly connected to the actuator.

26. (Original) The tool of claim 21, wherein the conveyor comprises a carriage and at least one rail, the carriage slidably attached to at least one rail and fixedly attached to the actuator.

27. (Canceled)

28. (Canceled)

29. (Previously Added) The tool of claim 12, wherein the tear-off edge extends along a third axis oblique to the second axis.

30. (Currently Amended) The A printing system comprising:  
a printer configured to print upon a tearable medium;  
an edge configured to extend along the tearable medium;  
a grasper configured to grasp the tearable medium while being moved to urge the tearable medium against the edge to sever the medium, wherein the edge extends along a first axis and wherein the grasper is movable along a second axis oblique to the first axis.

31. (Canceled)

32. (Previously Added) The system of claim 30 including a conveyor configured to move the grasper.

33. (Previously Added) The system of claim 32 including an actuator configured to move the grasper between a grasping state in which the grasper grasps the tearable medium and a releasing state in which the grasper does not grasp the tearable medium.

34. (Previously Added) The system of claim 33 including a controller configured to generate control signals, wherein the conveyor moves the grasper in response to the control signals and wherein the actuator moves the grasper in response to the control signals.

35. (Previously Added) The system of claim 30 including an actuator configured to move the grasper between a grasping state in which the grasper grasps the tearable medium and a releasing state in which the grasper does not grasp the tearable medium.

36. (Previously Added) The system of claim 30, wherein the grasper includes a first surface and a second opposite surface and wherein the first surface and the second surface are configured to engage opposite sides of the tearable medium.

37. (Previously Added) The system of claim 36, wherein at least one of the first surface and the second surface is movable relative to the other of the first surface and the second surface to move between a grasping state and a releasing state.

38. (New) The system of claim 37, wherein said at least one of the first surface and the second surface moves along the third axis perpendicular to the first axis.

39. (New) The tool of claim 7, wherein the third axis along which the first jaw is actuatable extends perpendicular to the second axis.